



**History:-** Started in November 2005, HISMAR is An ongoing project funded by the EU.

**Aims:-** To develop a prototype self-guiding autonomous underwater robot for the hull maintenance & ship repair industries.

**Purpose:-** Reduces maintenance time and costs;  
Reduces fuel consumption and fouling drag;  
Improves safety at sea;  
Environmental improvements to waterways by collecting and disposal of waste material.



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**Further information:** Can be found at the official HISMAR website (below) or in the published news reports.

**Partners:-**

Newcastle University (UK)  
Carnival (UK)  
GraalTech (Italy)  
Moscow State Technological University  
“Stankin” (Russian Federation)  
Polski Regestr Statkow (Poland)  
Robosoft (France)  
Royal Thai Navy (Thailand)  
Shipbuilders and Shiprepairers  
Association (UK)  
TechnoVeritas (Portugal)  
TEPAC (Germany)

**Website:-** <http://www.hismar.eu/>

**E-mail:-** [project@hismar.eu](mailto:project@hismar.eu)



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